

# rmf\_tool – A library to Compute (Refined) Mean Field Approximation(s)

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**How can we efficiently *analyze*, *understand* and *optimize* large scale stochastic systems?**

**Example: Load balancing systems**

→ compare policies & evaluate performance

**Mean Field Approximation technique can be help analyzing**

**rmf\_tool (refined mean field tool) aims to facilitate the useage**

# Some Intuition

System with:

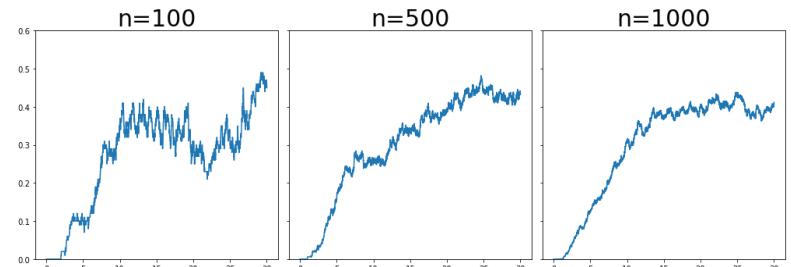
→  $n$  interacting objects

i.e. servers

→ finite states for each object

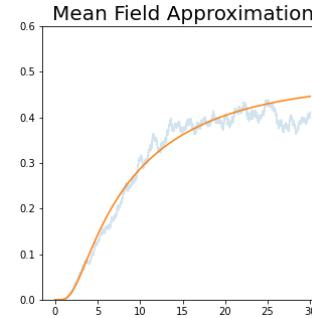
i.e. queue length

Problem: ⇒ exploding state space (  $n^S$  possible states)



↓  
 $n \rightarrow \infty$

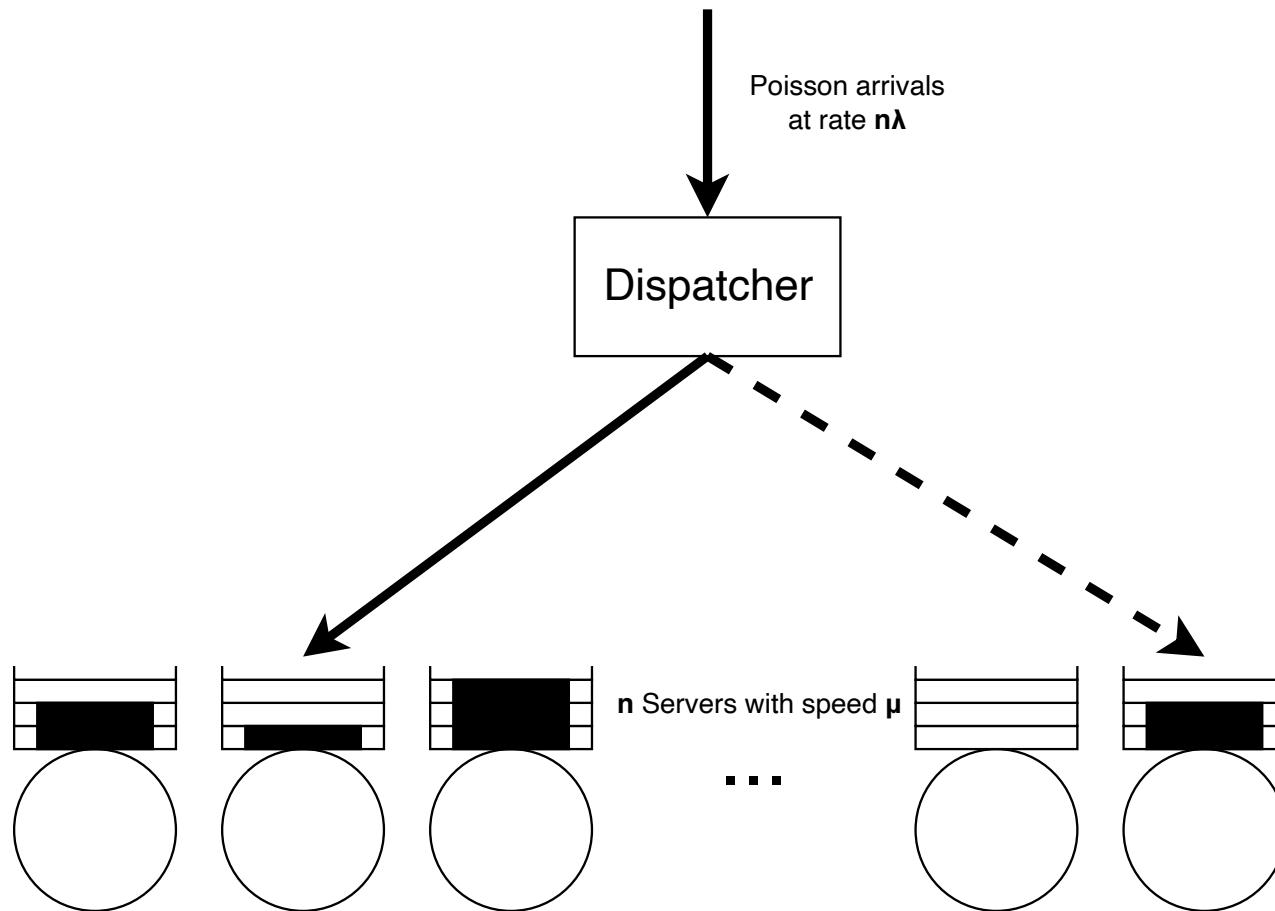
# Mean field can simplify



# ROADMAP

1. Load Balancing Example - JSQ(2)
2. Tool Features

## Example: Power-of-two-choices load balancing



## Model representation

$X^{(n)} = (X_0^{(n)}, \dots, X_K^{(n)})$  with  $X_i^{(n)}$  the fraction of servers having at least  $i$  jobs in the queue.

servers	server speed	arrival rate	buffer size
$n$	$\mu = 1$	$\lambda = 0.9$	K=9

State changes to servers with queue length  $i$

Arrival transition	Arrival Rate
$X \mapsto X + \frac{1}{n}e_i$	$n\lambda(X_{i-1}^2 - X_i^2)$

Removal Transition	Removal Rate
$X \mapsto X - \frac{1}{n}e_i$	$n\mu(X_i - X_{i+1})$

## Model Implementation

```
In [2]: import rmf_tool.src.rmf_tool as rmf

# This code creates an object that represents a "density dependent population process"
ddpp = rmf.DDPP()

# Set parameters
mu, _lambda, K = 1.0, 0.9, 9
```

```
In [4]: # Add transitions using mathematical formulation:
for i in range(K):
    if i >= 1:
        ddpp.add_transition(e(i), eval('lambda x: _lambda*(x[{}]*x[{}]-x[{}]*x[{}])'.format(i-1,i-1,i,i))) # arrivals
    if i < K-1 and i > 0:
        ddpp.add_transition(-e(i), eval('lambda x: mu*(x[{}]-x[{}])'.format(i,i+1))) # removals
```

# Calculating Mean Field Approximation and Simulation

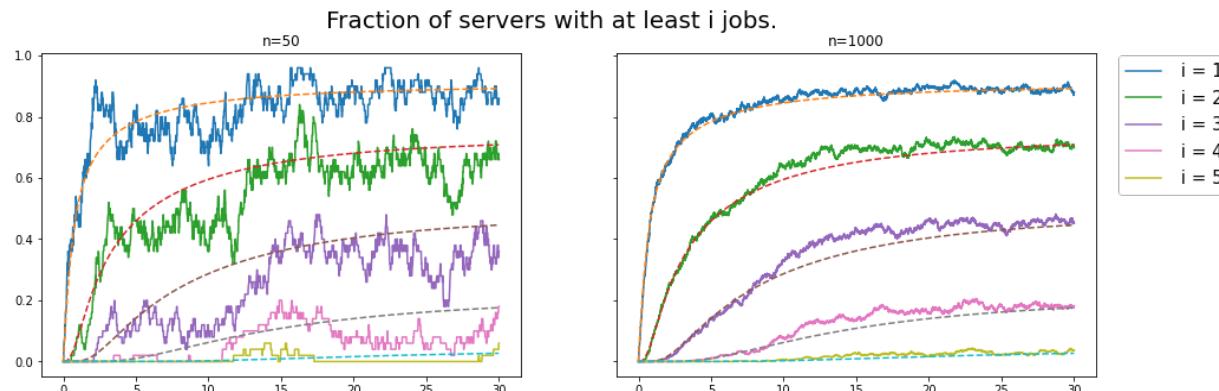
Mean Field Approximation is the average variation:

$$\dot{x}_i(t) = \underbrace{\lambda(x_{i-1}^2 - x_i^2)}_{\text{arrival}} - \underbrace{\mu(x_i - x_{i+1})}_{\text{removal}}, \quad x(0) = X(0)$$

```
In [15]: # Set initial state
ddpp.set_initial_state(e(0))

# Calculate mean field
T, x_transient = ddpp.ode(time=30)
```

```
In [16]: # Simulate a trajectory for N=50
T_n50, X_n50 = ddpp.simulate(N=50, time=30)
# and for N=1000
T_n1k, X_n1k = ddpp.simulate(N=1000, time=30)
```



## Tool features:

Mean Field Approximation (transient + steady state results) and Simulation for

### *Homogeneous Population Models*

→ systems with similar object behavior

Heterogeneous Population Models [Allmeier and Gast, 2021]  
(<https://arxiv.org/abs/2111.01594>)

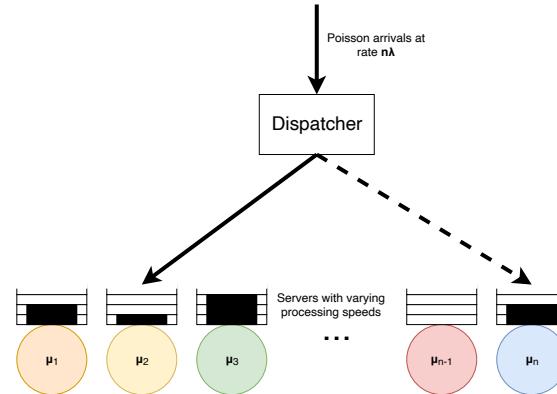
→ systems with varying object behavior

Refined Mean Field Approximation [Gast et al., 2019]  
(<https://www.sciencedirect.com/science/article/pii/S0166531618302633?via%3Dihub>)

→ increased accuracy  
→ especially important for  $n \approx 10 - 100$

## Examples:

### Power-of-two-choice model with varying server speeds



More examples: (Heterogeneous) epidemic model (SIR/SIS), caching policies, SSD garbage collection, load balancing models, etc.

# Thank you

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## References

rmf\_tool – A library to Compute (Refined) Mean Field Approximation(s) by Allmeier and Gast

→ [https://github.com/ngast/rmf\\_tool](https://github.com/ngast/rmf_tool) ([https://github.com/ngast/rmf\\_tool](https://github.com/ngast/rmf_tool))

Mean Field and Refined Mean Field Approximations for Heterogeneous Systems: It Works! by Allmeier and Gast

Size Expansions of Mean Field Approximation: Transient and Steady-State Analysis by Gast, Bortolussi, Tribastone

Expected Values Estimated via Mean Field Approximation are  $O(1/N)$ -accurate by Gast.