

An Axiomatic Perspective on the Performance Effects of End-Host Path Selection

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Motivating example: Lane splitting



(wikimedia.org)

 Banned in many places because of intuitive safety concerns

However:

 Research fails to confirm lane splitting as hazardous

Lane-splitting bans may be more costly than lane-splitting itself

• Lane-splitting bans reduce traffic speed

(M. Sperley, Motorcycle Lane-Sharing: Literature Review, 2010)

General insight: If problem is never properly characterized, solution may be worse than the problem

Parallel to end-host path selection:

- Widespread intuition that unregulated end-host path selection causes damage through oscillation
- Many proposals for path-selection regulation systems which introduce overhead
- Little rigorous research on extent and effects of oscillation problem

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Research question:

How exactly and *by how much* does oscillatory path selection decrease network performance?

Research approach:

Inspiration from axiomatic approach by Zarchy et al. (SIGMETRICS'20)

Previous analytical approaches in congestion-control research may be suitable for analysis or design of specific protocols...

... but not for the discovery of **fundamental constraints of the design space** (e.g., achievable optima and trade-offs with respect to different desirable properties)

axioms

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Axiomatizing Congestion Control

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The overwhelmingly large design space of congestion control protocols, along with the increasingly diverse range of application environments, makes evaluating such protocols a daunting task. Simulation and experiments are very helpful in evaluating the performance of designs in specific contexts, but give limited insight into the more general properties of these schemes and provide no information about the *inherent* limits of congestion control designs (such as, which properties are simultaneously achievable and which are mutually exclusive). In contrast, traditional theoretical approaches are typically focused on the design of protocols that achieve to specific, predetermined objectives (e.g., network utilly maximization), or the analysis of specific protocols (e.g., from control-theoretic perspectives), as opposed to the inherent tensions/derivations between desired properties.

To complement today's prevalent experimental and theoretical approaches, we put forth a novel principled framework for reasoning about compession control protocols, which is inspired by the axiomatic approach from social choice theory and game theory. We consider several natural requirements ("axioms") from congestion control protocols – e.g., efficient resource-utilization, loss-avoidance, fairness, stability, and TCP-friendliness – and investigate which combinations of these can be achieved within a single design. Thus, our framework allows us to investigate the fundamental tradeoffs between desiderata, and to identify where existing and new congestion control architectures fit within the space of possible outcomes.

 $\text{CCS Concepts:} \bullet \textbf{Networks} \rightarrow \text{Network protocols};$

ACM Reference Format:

Doron Zarchy, Radhika Mittal, Michael Schapira, and Scott Shenker. 2019. Axiomatizing Congestion Control. Proc. ACM Meas. Anal. Comput. Syst. 3, 2, Article 33 (June 2019), 33 pages. https://doi.org/10.1145/3326148

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Axiomatic approach: A simple example

- 1) Represent protocol behavior in single-bottleneck discrete-time model
- 2) Assess protocol behavior w.r.t. axiom metrics
- 3) Identify fundamental constraints of the protocol behavior



THEOREM 3. Any loss-based protocol that is α -fast-utilizing, β -efficient, and ϵ -robust, for $\epsilon > 0$, is at most $\frac{3(1-\beta)}{(4(\frac{C+r}{1-\epsilon})-\alpha)(1+\beta)}$ -TCP friendly.
(Zarchy et al.)



Axiomatic perspective on end-host path selection

 We extend Zarchy et al.'s axiomatic CC approach to joint congestion control and path selection (MPCC) → Multiple bottleneck links available for selection

2) We are interested in the worst-case effects of oscillatory path selection

- \rightarrow Greedy path selection: Switch to least utilized path with given probability m
- → Sequential multi-path: Every sender uses only one path at a given moment
- \rightarrow All paths have same capacity s.t. differences in load matter for attractiveness
- \rightarrow Senders have same RTT, so their reactions are strongly correlated
- 3) We test different policies for handling path switch in CC algorithm
 - \rightarrow Reset *r* of congestion window upon path switch
 - \rightarrow Function $\alpha(t)$ regulating congestion-window growth after path switch

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Capacity C Capacity C

Capacity C

Characterization of path selection (Part 1)

1) LLN-based approximation of stochastic process by **expected dynamics**



- 2) Identification of common oscillation pattern (*P*-step oscillation)
- 3) Derivation of dynamic equilibria produced by oscillation pattern



Characterization of path selection (Part 2)

4) Rating of MPCC equilibria according to **axiom metrics**

 $\epsilon(MPCC(\alpha, \beta, m, r)) \ge \begin{cases} P \cdot \hat{f}^{(P-1)}/C & \text{if } \hat{f}^{(0)} \le C/P & \text{(Lossless equilibrium)} \\ \beta \cdot (1-m)^{P-1} & \text{otherwise} & \text{(Lossy equilibrium)} \end{cases}$

5) Rating of underlying CC protocol in absence of path selection

$$\forall \pi \in \Pi. \epsilon \left(CC_i(\alpha, \beta) \right) = \frac{\beta \cdot C/P}{C/P} = \beta$$

6) Comparison of multi-path axiom scores and single-path axiom scores





Characterization of path selection (Part 3)

 7) Elicitation of insights from comparison-based analysis For example:

> A high path-migration rate harms efficiency. However, a moderate migration rate is preferable to a very low migration rate.



Characterization of path selection (Part 3)

 7) Elicitation of insights from comparison-based analysis For example:

A high path-migration rate is associated with high fairness.

Cwnd variance as fairness metric

$$\exists t' > 0. \quad \forall t > t'. \quad \bigvee_{i \in A} \left[cwnd_i(t) \right] \le \eta$$

Scenario without path selection: Perfect fairness (Zarchy et al.)

 $\eta \left(CC_i(\alpha,\beta) \right) = 0$

Scenario with path selection:

Markov process

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 10^{7}

Lossless, α_1 , minimal

Lossless, α_1 , maximal

Lossless, $\alpha_{\rm S}$, minimal

Lossless, $\alpha_{\rm S}$, maximal

Characterization of path selection (Part 3)

7) Elicitation of insights from comparison-based analysis
 For example

A high path-migration rate harms efficiency, loss avoidance and stability, but improves fairness. However, even for metrics that benefit from low migration, a moderate migration rate is preferable to a very low migration rate.

Path selection may worsen efficiency because the utilization plunge created by loss is compounded with out-migration from the loss-experiencing path.

A hard reset of the congestion window upon path switch improves network stability, but harms efficiency.

Conclusion

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Questions?

How exactly and *by how much* does oscillatory path selection decrease network performance?



Central finding:

Oscillation from path selection is not necessarily harmful! For moderate migration rates, it is even preferable to no path selection at all.